

Fig. 1

FIG. 2 is a schematic diagram of a system 200 for controlling a vehicle 210. The system 200 includes a controller 280, a sensor 282, an actuator 284, and a communication module 281. The controller 280 is connected to the sensor 282 and the actuator 284. The communication module 281 is connected to the controller 280 and a network 260. The network 260 is connected to a server 270. The server 270 is connected to a database 275. The database 275 is connected to a user interface 290. The user interface 290 is connected to a user 295. The user 295 is connected to the vehicle 210. The vehicle 210 is connected to the sensor 282. The sensor 282 is connected to the controller 280. The controller 280 is connected to the actuator 284. The actuator 284 is connected to the vehicle 210. The vehicle 210 is connected to the network 260. The network 260 is connected to the server 270. The server 270 is connected to the database 275. The database 275 is connected to the user interface 290. The user interface 290 is connected to the user 295. The user 295 is connected to the vehicle 210.

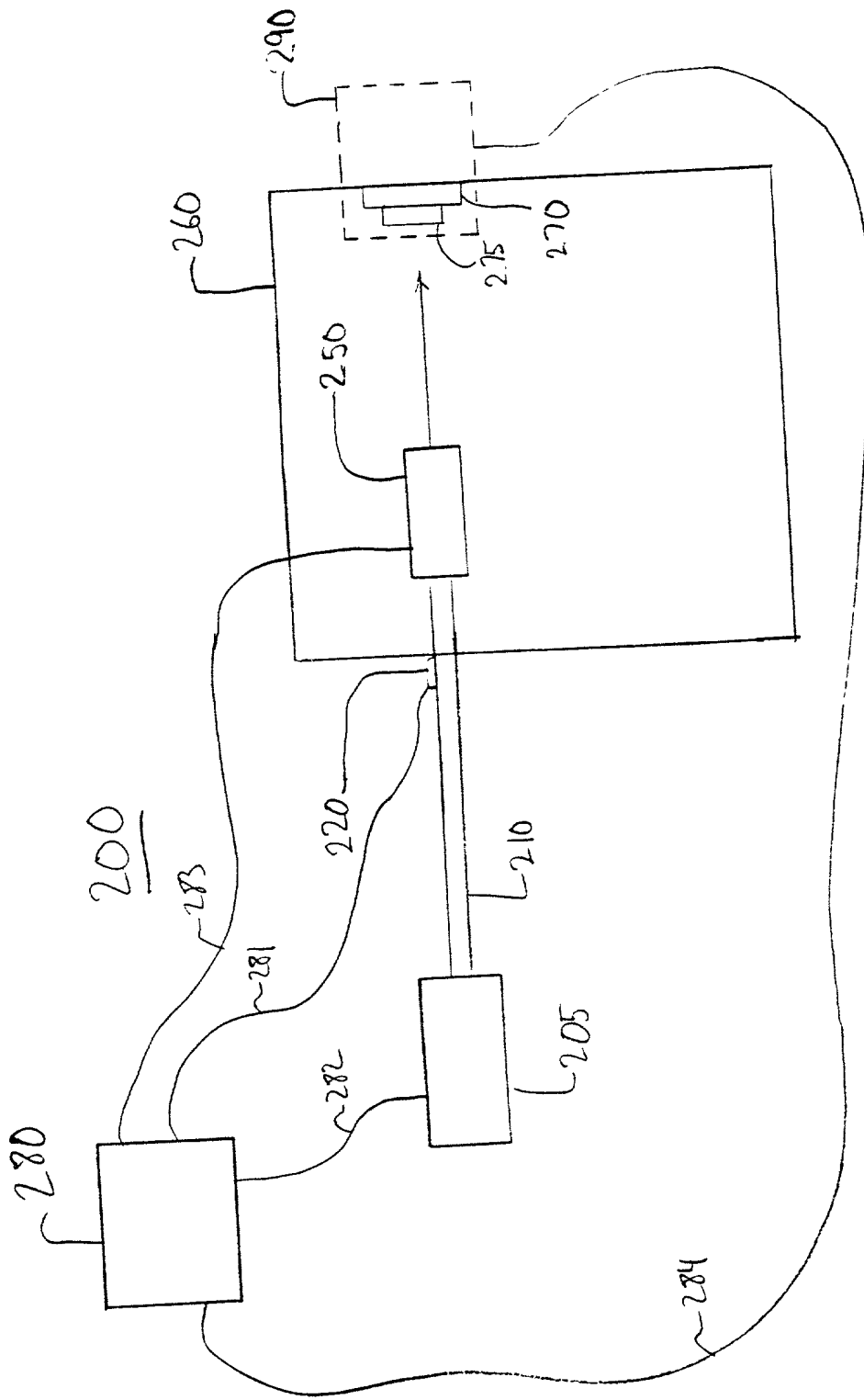
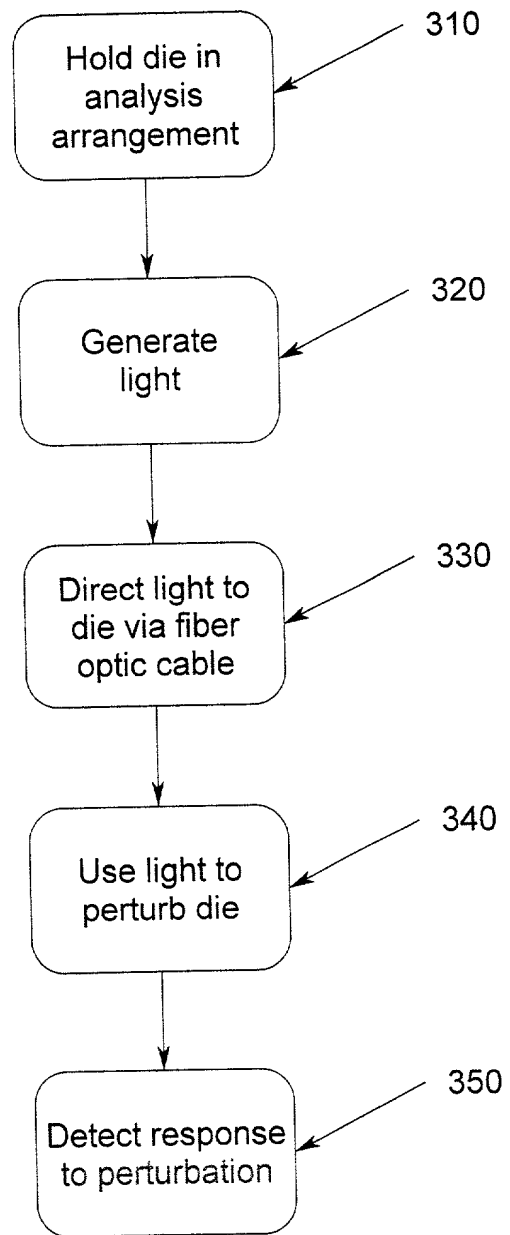


Fig. 2



**Fig. 3**